



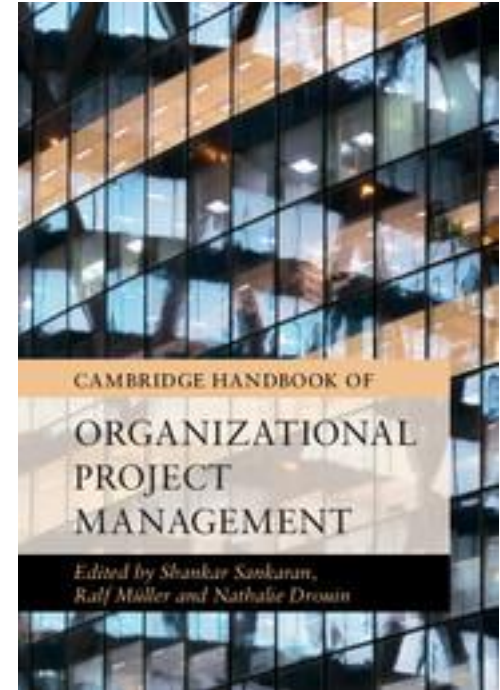
NORWEGIAN
BUSINESS SCHOOL

“Når planen blir problemet”

Shared Space for Organizations: Enablers for Innovative Projects

*Chapter 24 in the Cambridge Handbook of
Organizational Project Management*

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Quote from a successful project manager working in an uncertain context (ASML)

*“I only make detailed project plans for the short term
Because I don’t know yet what will happen on the long term”*

“Long term is anything that happens 48 hours from now”

Developing machines that cost over 100
million euro without detailed plans?
What’s going on?



Unk-Unks in Project Management



Known knowns

«There are things we know we know»

We know what to do, we know how and we know when

Known Unknowns

«There are things we know we don't know»

We know what we don't know, we recognize the problem
(e.g. we know what to do, but we don't know how much time it will take)

Unknown Unknowns

«There are things we don't know we don't know»

We don't know what we don't know, we don't recognize the problem
(e.g. we don't even know what to do, let alone how long it will take us)

Project planning and unknown unknowns

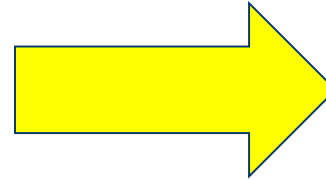


Known knows

WBS
Gantt charts
CPM
Network planning

Known Unknowns

WBS
Gantt charts
PERT-CPM
Network planning



Unknown Unknowns

?
?
?

In lack of anything better,
tools designed for
“predictable” projects are
forced on projects with high
levels of uncertainty



What do we usually do in traffic when things get complex and unpredictable?



Unintended consequences of too many rules, demarcations, and signs

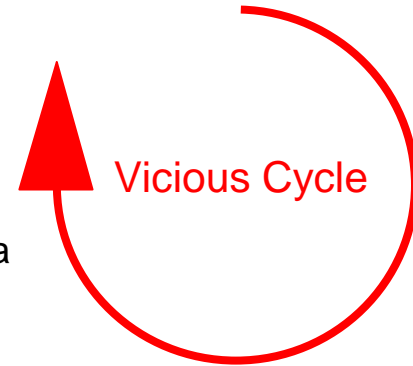
- reduced thinking & creativity
- a-social behavior (non-communication)
- mistakes due to mixed signals or overload of signals

Self-fulfilling prophecy:
If you treat people like
idiots, they will tend to
fulfill your expectations



(Un-)Intended effects of street regulations

- Intended effect: reduction of accidents caused by an increase of motorized traffic
- Unintended effects:
 - regulations do not stimulate non-motorized traffic (the streets are not a pleasant place to be)
 - This increases motorized traffic even further
 - and consequently, increasing the perceived need for even more regulations



Decision trap:
it seems to be good at first,
but backfires later

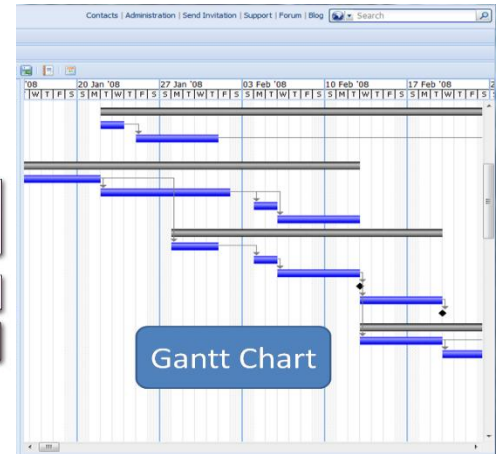
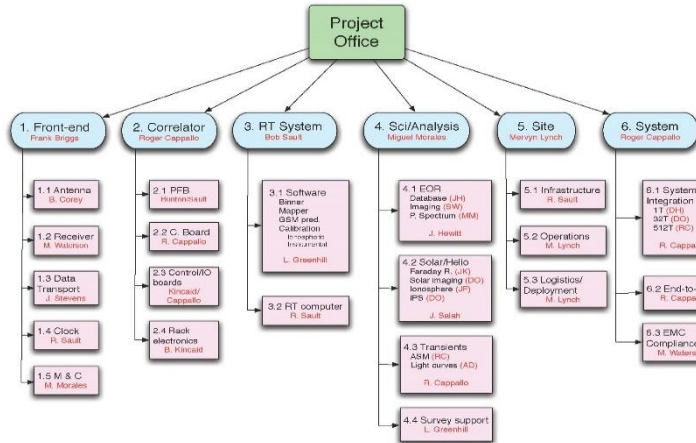
From urban planning to project planning, to many rules, demarcations, and signs

lead to:

- reduced thinking & creativity
- a-social behavior (non-communication)
- mistakes due to mixed signals or overload of signals

| Test Plan | | |
|-----------|---------------------------|-----------|
| Test # | Test | Owner |
| 1 | Battery Voltage | Felix |
| 2 | USB Passthrough | Felix |
| 3 | Fuel-Gauge | Felix |
| 4 | Water Sensor | Felix |
| 5 | Tail-Motion (Complete) | Felix/All |
| 6 | Battery Capacity | Felix |
| 7 | Initial Buoyancy | Zak/John |
| 8 | Waterproof Box | Seaver |
| 9 | Skin Structural Integrity | Seaver |
| 10 | Final Buoyancy | Zak/John |
| 11 | Forward Motion | All |
| 12 | Turn Radius | Felix/All |
| 13 | Fully Integrated System | Felix/All |
| 14 | Aesthetics | All |

| Test Plan | | |
|------------------|--|--|
| Test Description | | |
| 1 | Charge battery for operation, charge on smart charger to safest full charge and record voltage present, record and publish for subsystem demo requirement. | |
| 2 | Test USB Passthrough for functionality, ensure operation. Record and publish results for subsystem demo requirement. | |
| 3 | Ensure fuel gauge works as stated, not faulty. Check measurements with voltmeter for consistency. Record and publish res subsystem demo requirement. | |
| 4 | Wire up sensor and ensure performance as expected (expose to water). Record and publish results for subsystem demo requirement. | |
| 5 | Test complete 3 section model. Continual refinement until team is happy. Present to KLK and Rick Lux and next available in everyone is satisfied move on. If not, continue tweaking motion until everyone is happy. Test will also serve to verify functs pump, solenoids, relay shield, and arduino. Record and publish results for subsystem demo requirement. | |
| 6 | Run tail section in kiddie pool on a fully charged battery. Ensure sufficient run time before fuel-gauge indicates charge recce Record and publish results for subsystem demo requirement. | |
| 7 | After the box and tail sections have been mated, completely submerge model in water and observe buoyancy characteristics. Modify amount of air in "floaties" to account for pitch and roll until a level, neutrally buoyant status is achieved. If unable to produce desired characteristics, modify placement of interior components or add weights as necessary until neutrally buoy balanced (roll and pitch). Record and publish results for subsystem demo requirement (video). | |
| 8 | After box has been constructed, and any leak paths induced (passthroughs, etc.), take completed box (empty) and submerge for 1 minute (pool or tow tank). After the test has been conducted, remove box from water and check for any leak paths. If box, locate source, modify, and rerun test until successful completion. Record and publish results for subsystem demo req. After spandex material has been purchased, construct an approx. 6" square sample to check for structural characteristics by constructing entire skin model. Dip material in liquidified polymer material and hang to dry until set. Strain composite material evaluate dynamic characteristics. Ensure that material is able to strain (to some degree) without separation of layers, note approximate degree of safe strain if failure occurs to use in constructing the full skin model to size appropriately. Record ar results for subsystem demo requirement. (Max strain tested without failure). | |
| 9 | After complete model has been assembled, ensure that skin hasn't thrown off buoyancy characteristics. Readjust air in "fo and move components if necessary to regain proper alignment characteristics while submerged. | |
| 10 | Take completed fish in water, ensure that motion from lab tests produces forward propulsion as expected. Document trial | |
| 11 | Perform C-turn and slow turn sequences in open water (pool). Ensure KLK can be present to okay motion. If KLK is unsatisfis continue refining program and repeat until satisfied. | |
| 12 | Test complete fish in water (pool), tweak until everyone is satisfied by consensus. Invite KLK and Rick to view demonstration performing swimming protocol including straight line motion, pauses, C-turn, and slow turn. Take consensus to see if every satisfied. If not, refine programming and repeat | |
| 13 | Get minimum of 10 fill out on a scale of 1-10 how "fishy" it looks (1-that's not a fish, 10-looks real), and provide feedback to make it better. Have KLK do the same. Conduct "Test" at Imagine RT booth. | |



Drawing the analogy

- Motorized traffic →
- Non-motorized traffic (pedestrians, cyclists) →
- Accidents →
- exploitation projects = using existing knowledge
- exploration projects = developing new knowledge
- “success trap in product development” = ever-increasing efforts devoted to exploitation projects, neglecting exploration

Self-reinforcing process

- PM tools we have favor projects with predictable outcomes → exploitation
- Because these projects are successful, they get more funding, more resources, more attention
- Sometimes these projects even get their own departments or business units (segregation/demarcation)
- This works well on the short term, but organizations need new ideas, new knowledge to survive on the long term as well → success trap
- Therefore it is called a “trap”, because it discourages exploration



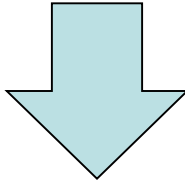
Can we prevent this trap (accident)?

Shared space

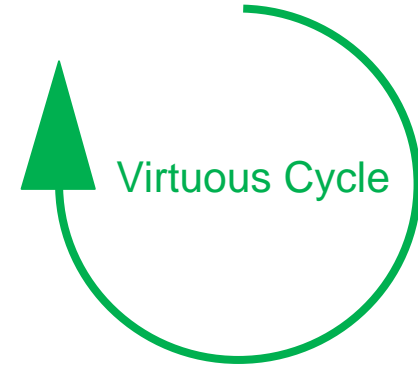
- Dutch traffic engineer Hans Monderman introduced this concept in 1982
- His aim was to reduce accidents and congestion and to increase the flow of traffic
- Shared space promotes a sense of vigilance and responsibility by reducing demarcations and physical distinction between the streets and pedestrian areas
- In the absence of rules, and the predictability and certainty that traffic demarcations used to provide, street users need to rely on other signals
- Communication and eye contact become the norm, while the average speed of traffic is reduced

Counterintuitive effects of removing street regulations

- Instead of focusing on preventing accidents
- Focus shifts to encouraging non-motorized traffic and reduction of speed of motorized traffic



- Less accidents
- Slower average speed, but more throughput
- Increase of non-motorized traffic



How to prevent “accidents” in project organizations?

- “Accident”: investing too much in exploitation projects and killing exploration projects because they don’t fit the existing tools and reporting rules
- More structure? More rules? More demarcations between people?
- Or less/no structure? (like the shared space in traffic)

How to break down the learning silos?

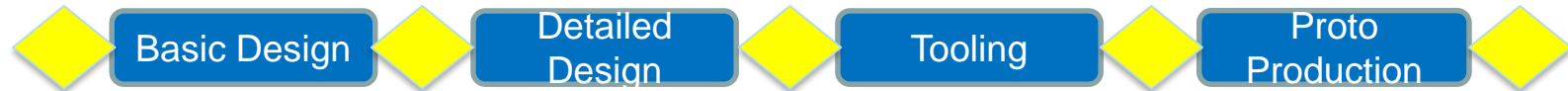
We need structures or tools that boost creativity, flexibility, communication, knowledge sharing, learning, room for trial and error, room to make mistakes

Enablers for sharing space in projects:

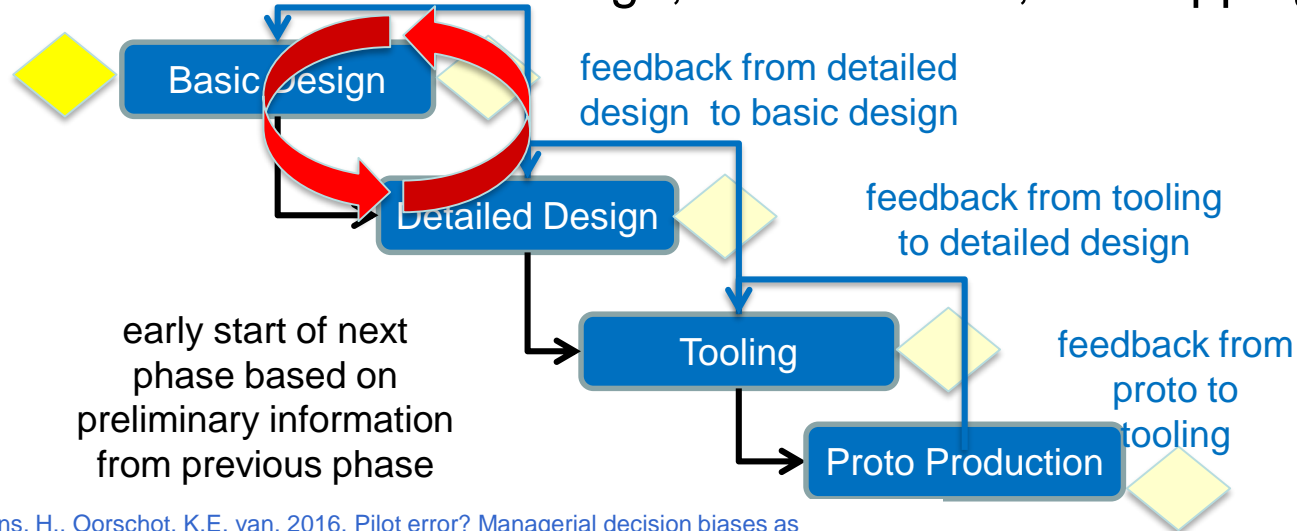
- within the project
- within the organization
- within the project network (multiple organizations)

A clash of approaches?

Sequential Design, structured Stage-Gate approach (Cooper 2008)



Concurrent Design, less structure, overlapping of phases



Risk of iterations,
more costs

Faster learning,
earlier finish



More and different milestones

- Milestones are commonly used to plan meetings, arrangements, celebrations, etc.
- So, milestones help communication between project stakeholders
- Often, milestones are event-oriented, for example:
 - Milestone 2 is reached when the design is finished
 - Milestone 4 is reached when the foundation for the new building is ready
- But, in projects with high levels of uncertainty, how do you know which event can or will happen? And when?
- **Time-oriented milestones** are better:
 - Milestone 2 is on January 20
 - Regardless of what has been done or what is finished, the team will have the opportunity to meet on that day and everyone knows that this is going to happen (Gersick, 1994)

Agile development

- An agile method focuses on adapting to change through highly iterative development and test cycles (Conboy, 2009; Dingsøy, Dyba, & Moe, 2010)
- Product requirements are discussed and prioritized with customers and placed in the backlog for the next iterative cycle (Dingsøy, Dyba, & Moe, 2010; Fowler & Highsmith, 2001)
- Note that this agile method also has time-oriented milestones: the team knows beforehand that it will meet with the customer after every cycle/iteration, but the team doesn't know yet what will be delivered in each cycle

Sharing space in organizations

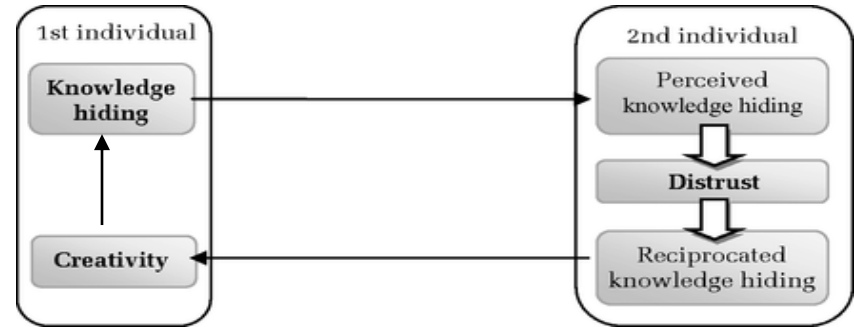
- Co-location (*if full-time co-location is impossible, part-time co-location is still better than separation*)
- Aligning executives and board members: sharing a long-term vision instead of short-term focus on profits
- Big picture thinking: goal alignment between departments, remove conflicting goals

Sharing space in project networks

Get rid of knowledge protection rules and regulations

- knowledge hiding/protection will reduce trust between the collaborating organizations, which reduces creativity of these organizations (Černe, Nerstad, Dysvik, & Škerlavaj, 2014):

Reciprocal Distrust Loop
Illustrating the Knowledge
Hiding-Creativity Relationship



Back to ASML (the company with cowboys)

- Boosting creativity by always aiming as high as possible (but keeping some slack by not telling the customer exactly how high you aim)
- Sharing space by having a fixed pool of engineers for each project (no knowledge leakage, no waste of time)
- Always protecting engineers, also in downturns (no knowledge leakage)
- Local sourcing (short lines of communication)

Sharing space in projects

Sharing space in organizations

Sharing space in networks

Without rules?



Different rules

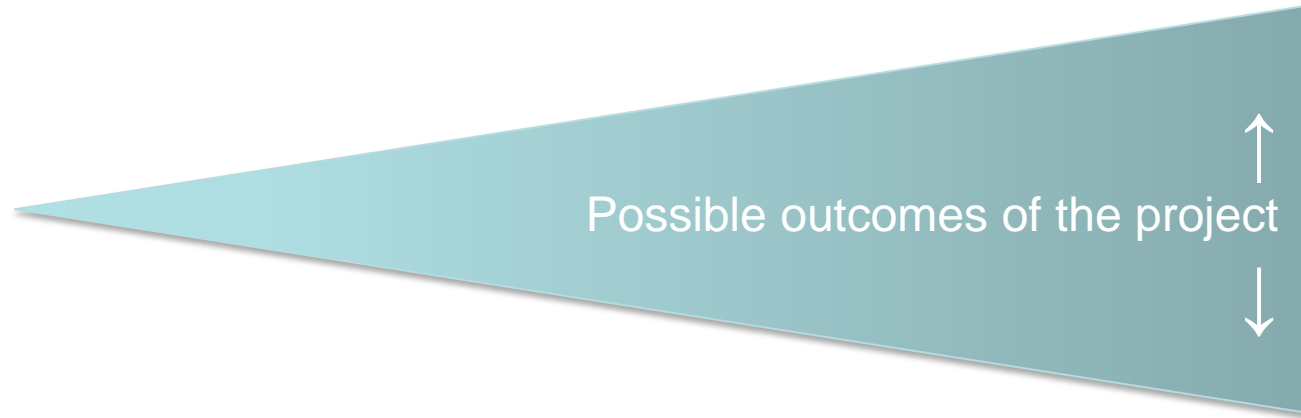
- If you look closely, there are traffic “rules” in India

- Use horn
- Eye contact
- Give and take
- Drive slowly, but keep moving
- Communication
- Learning
- Iteration
- Progress



These rules do not **limit** our ability to think.
Instead, they **enable** us to see through the complexity,
to deal quickly with unexpected events

Project planning and unknown unknowns



Known knowns

WBS
Gantt charts
CPM
Network planning

Known Unknowns

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PERT-CPM
Network planning

Unknown Unknowns

Break-down of silo's
Multiple iterations
Trial and error
Time-oriented milestones
Flexibility
Communication
Knowledge sharing

Conclusions

- The best project plan may be no plan at all, or at least a less detailed plan
- The concept of shared space in traffic has shown that removing street regulations leads to a different kinds of “rules”: more eye contact between motorized and non-motorized traffic, and as a result: more safety and an increased flow of traffic
- Let this example be an inspiration for project organizations!

Thank you for your attention!



Go your own road – Erik Johansson